## In a nutshell: Muller's method

Given a continuous real-valued function *f* of a real variable with three initial approximations of a root  $x_{-2}$ ,  $x_{-1}$  and  $x_0$  where  $|f(x_{-2})| \ge |f(x_{-1})| \ge |f(x_0)| > 0$ , rearranging them if necessary. If one is zero, we have already found a root. This algorithm uses iteration, quadratic interpolation and a solution to the quadratic equation to approximate a root.

Parameters:

$\mathcal{E}_{step}$	The maximum error in the value of the root cannot exceed this value.
$\mathcal{E}_{abs}$	The value of the function at the approximation of the root cannot exceed this value.
Ν	The maximum number of iterations.

- 1. Let  $k \leftarrow 0$ .
- 2. If k > N, we have iterated N times, so stop and return signalling a failure to converge.
- 3. If  $|f(x_{-2})| \ge |f(x_{-1})| \ge |f(x_0)| > 0$  does not hold, rearrange the values so as to ensure this is true.
- 4. The next approximation to the root will be  $x_k$  plus the smaller root of the quadratic polynomial that interpolates the points  $(x_{k-2} x_k, f(x_{k-2})), (x_{k-1} x_k, f(x_{k-1}))$  and  $(0, f(x_k))$ .

$$a \leftarrow \frac{\left(f\left(x_{k-1}\right) - f\left(x_{k-2}\right)\right)x_{k} + \left(f\left(x_{k-2}\right) - f\left(x_{k}\right)\right)x_{k-1} + \left(f\left(x_{k}\right) - f\left(x_{k-1}\right)\right)x_{k-2}}{(x_{k-1} - x_{k-2})(x_{k-2} - x_{k})(x_{k} - x_{k-1})} \\ \left(f\left(x_{k-1}\right) - f\left(x_{k-2}\right)\right)x_{k}^{2} + 2\left(\left(f\left(x_{k-2}\right) - f\left(x_{k}\right)\right)x_{k-1} + x_{k-2}\left(f\left(x_{k}\right) - f\left(x_{k-1}\right)\right)\right)x_{k} \\ - \left(f\left(x_{k-2}\right) - f\left(x_{k}\right)\right)x_{k-1}^{2} - \left(f\left(x_{k}\right) - f\left(x_{k-1}\right)\right)x_{k-2}^{2}}{(x_{k-1} - x_{k-2})(x_{k-2} - x_{k})(x_{k} - x_{k-1})} \\ c \leftarrow f\left(x_{k}\right)$$

If a = 0, the three points are in a straight line, so let  $x_{k+1} \leftarrow x_k - \frac{c}{b}$ ;

otherwise, if  $b^2 - 4ac < 0$ , the roots are imaginary, so return signalling a failure to converge;

otherwise, if 
$$b > 0$$
, let  $x_{k+1} \leftarrow x_k - \frac{2c}{b + \sqrt{b^2 - 4ac}}$ ,

if 
$$b < 0$$
, let  $x_{k+1} \leftarrow x_k - \frac{2c}{b - \sqrt{b^2 - 4ac}}$ ,

otherwise it must be that b = 0, so let  $x_{k+1} \leftarrow x_k - \sqrt{-\frac{c}{a}}$ .

- a. If  $x_{k+1}$  is not a finite floating-point number, so return signalling a failure to converge.
- b. If  $|x_{k+1} x_k| < \varepsilon_{\text{step}}$  and  $|f(x_{k+1})| < \varepsilon_{\text{abs}}$ , return  $x_{k+1}$ .
- 5. Increment *k* and return to Step 2.

## Convergence

If h is the error, it can be show that the error decreases according to  $O(h^{\mu})$  where  $\mu \approx 1.8393$  is the real root of  $x^3 - x^2 - x - 1 = 0$ .